

Lecture 21. Encoding Q-convolutional codes

21.1

Given a polynomial stabilizer matrix

$$S(D) = (X(D) \mid Z(D))$$

transform it into the form

$$S_0(D) = \{0 \mid I\}$$

Then: encoding of the code with stabilizer $S_0(D)$ is trivial, insert $n-k$ qubits (qudits) in the state $|0\rangle$ after every block of k inputs.

21.2 Local transformations:

apply the local Clifford gate on qubit i in every block of size n

$$K = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \Rightarrow \hat{K} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \in \mathbb{F}_2^{2 \times 2}$$

$$P = \begin{pmatrix} 1 & \\ & i \end{pmatrix} \Rightarrow \hat{P} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \in \mathbb{F}_2^{2 \times 2}$$

These gates preserve the weight of the stabilizers.

21.3 Two-qubit gates

(2)

$\widetilde{\text{CNOT}}^{(i,j)}$ acts on a pair of positions i, j

- add X from control to target
- add Z from target to control

$$\widetilde{\text{CNOT}}^{(i,j)} = \left[\begin{array}{cc|c} i & j & \\ \hline 1 & 1 & \\ & 1 & \\ \hline & & 1 \\ & & 1 & 1 \\ \hline X & Z & \end{array} \right] : \begin{matrix} i \\ \text{within one block} \\ j \end{matrix}$$

CNOT spanning more than one block:

$$i, j+l \cdot n \quad i \not\equiv j \pmod{n}$$

\Rightarrow if $i=j \pmod{n}$

results in an infinite
cascade of CNOTs

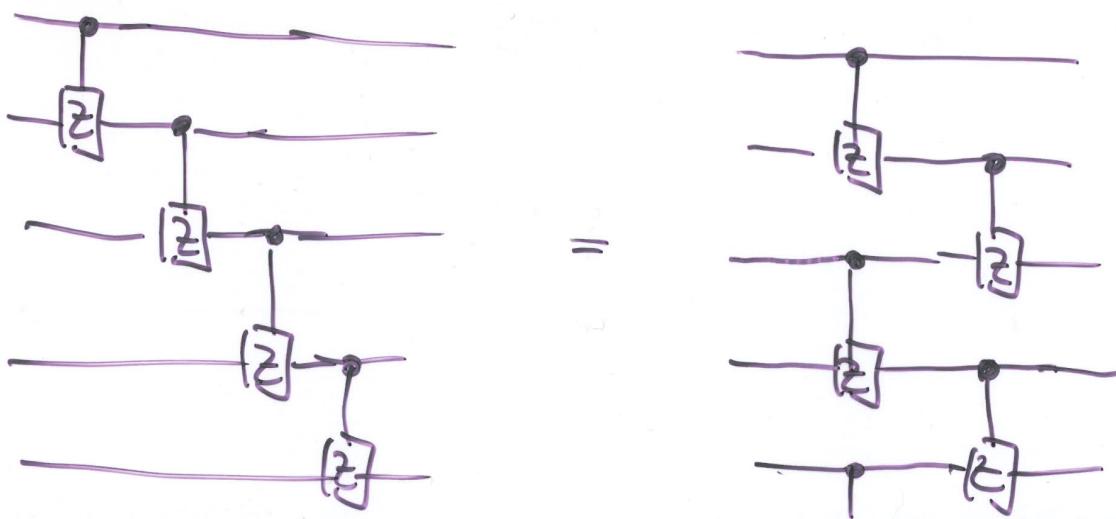
$$\widetilde{\text{CNOT}}^{(i,j+ln)} = \left[\begin{array}{cc|c} i & j & \\ \hline 1 & D^l & \\ & 1 & \\ \hline & & 1 \\ & & D^{-l} & 1 \\ \hline & & & \end{array} \right] \quad 1 \leq i, j \leq n$$

\Rightarrow We may negative powers of D in the transformed stabilizer (Laurent polynomials)
Multiply by some power of D at the end (shift the stabilizers)

21.4

Controlled phase gates

(4)

there is no
no. (3)finite depth
circuit!

$$\widetilde{\text{SIGN}}^{(i, j+ln)} = \left[\begin{array}{c|cc} 1 & 0 & D^l \\ -1 & D^{-l} & 0 \\ \hline 1 & & 1 \end{array} \right] \quad \text{for } i \neq j \bmod n$$

different qubits
in the blocks

$$\widetilde{\text{SIGN}}^{(i, i+ln)} = \left[\begin{array}{c|cc} 1 : D^{-l} + D^l & & \\ \dots & - & - \\ 0 & 1 & \\ \hline x & z & \end{array} \right] = \widetilde{P}_e$$

$l \neq n$
operating on
the same qbit
in different blocks

$$\widetilde{P} = \widetilde{P}_0 = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$

21.5 Trapezoidal-Lemma

(5)

Use local gates H, P as well as
the pseudo-local gate P_e to throw form
a stabilizer of the form

$$(f(D) | g(D)) = s$$

acting on qubit i in several blocks m_0

$$(h(D) | 0)$$

where $h(D) \in F_2[D, D^{-1}]$ (Laurent poly.)

The stabilizer s is a tensor product of some
Pauli matrices commuting with all its shifted
versions

$$s = \dots I \otimes Y \otimes Z \dots A I \dots$$

$$s' = \dots I \otimes \cancel{B} \otimes Z \dots A I \dots$$

As s and s' commute, A and B must be the
same Pauli matrix, w.l.o.g. $A=B=Z$.

Now $f(D)$ and $g(D)$ are of the following form

$$f(D) = D^{\gamma_0} + \dots + D^{\gamma_0}$$

$$g(D) = \underline{D^{\mu_0} + \dots + g_{r_0} D^{\gamma_0}} + \dots + \underline{g_{r_1} D^{\gamma_1} + \dots + D^{\mu_1}}$$

\tilde{P}_e with $\ell = \min(\underline{\gamma_0 - \mu_0}, \underline{\mu_1 - \gamma_0})$

$$g'(D) = (D^{-\ell} + D^\ell) \cdot f(D) + g(D)$$

\Rightarrow The degree of $g'(D)$, i.e. the difference $\mu_1 - \mu_0$, is strictly smaller than that of $g(D)$ given by $\mu_1 - \mu_0$.

(Swap f and g , as \tilde{P}_e changes the \mathbb{Z} -part
if $\deg(g) < \deg(f)$)

Repeat this step, until the new polynomial is zero, possibly using \tilde{H} to swap f and g

\Rightarrow At the end, we have an X -only solution, but not necessarily of weight one!

(7)

Sketch of the general algorithm:

(i) Use CNOT gates between different positions to reduce the degrees in the X-part of the first row, actually: we can achieve a form

$$\begin{array}{c} \text{trapezoid} \\ \text{lemma} \end{array} \quad \left(\begin{array}{cccc|ccccc} f_1(D) & 0 & \dots & 0 & g_1(D) & g_2(D) & \dots & g_n(D) \\ f'_1(D) & 0 & \dots & 0 & 0 & g_2(D) & \dots & g_n(D) \end{array} \right)$$

(ii) Use Hadamard to obtain

$$\left(\begin{array}{ccccc|ccccc} f'_1(D) & g_1(D) & \dots & g_n(D) & 0 \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \end{array} \right)$$

(iii) repeat step (i) to obtain

$$\left(\begin{array}{ccccc|ccccc} f''_1(D) & 0 & \dots & 0 & g'_1(D) & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \end{array} \right)$$

(iv) use the trapezoid lemma to obtain

$$\left(\begin{array}{ccccc|ccccc} f'_1(D) & 0 & \dots & 0 & 0 & 0 & \dots & 0 \end{array} \right)$$